# **CCR-67V Series**

DC-67 GHz, Non-terminated Latching SPDT Coaxial Switch

PARTNUMBER	DESCRIPTION				
CCR-67V DC-67 GHz, SPDT, Latching Coaxial Switch					
CR-67V	Elite, DC-67 GHz, SPDT, Latching Coaxial Switch				

The CCR-67V series is a Latching SPDT, electromechanical coaxial switch designed to switch a microwave signal from a common input to either of two outputs. This switch is designed to operate in the frequency range from DC to 67 GHz featuring excellent RF and mechanical performance with broadband operation, high isolation and low insertion loss making them ideal for test and measurement equipment and microwave communication systems. The CCR-67V switches incorporate 1.85 mm high performance connectors and are compatible with two most common mounting hole patterns which make them interchangeable with a wide variety of switches.



ENVIRONMENTAL AND PHYSICAL	L CHARACTERISTICS
Storage Temperature	–55°C to 90°C
Operating Temperature Commercial Model CCR-67V Elite Model, CR-67V CR-67V w/ indicator contacts	–25°C to 65°C –55°C to 85°C –45°C to 85°C
Vibration <sup>1</sup> , 10 ~ 2000 Hz, 300 s MIL-STD-202 Method 204, Condition C	10 G peak
Shock, Half-Sine Pulse MIL-STD-202 Method 213, Condition D	500 G peak
Moisture Resistance <sup>2</sup>	95% RH Non-condensing
Mechanical Life	2,000,000 cycles (min)
Mechanical Life w/ indicator contacts	1,000,000 cycles (min)
Connector Type	1.85 mm (V)
Weight	1.41 oz. approx (40 g)

<ol> <li>Non-operating</li> </ol>	ting	Non-opei	1
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2. When moisture seal option is selected

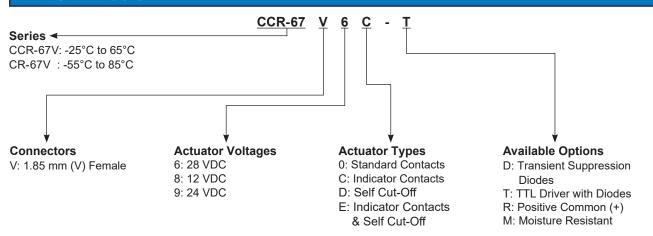
ELECTRICAL CHARACTE	RISTICS
RF Contacts	Break before make
Frequency Range	DC – 67 GHz
Characteristic Impedance	50Ω
Switching Time	20 ms max
Actuation Voltage (VDC) 20°C	12 24 28
Actuation Current (mA)	150 TBD TBD
TTL/Decoders Voltage/Current <sup>1</sup> Low Level (Logic 0) High Level (Logic 1)	0.0 ~ 0.7 V / 3.2 mA Max at 0.7 V 2.4 ~ 5.5 V / 80 μA Max at 2.4 V
Indicator Contact Rating <sup>2</sup>	30 Vdc, 50 mA max
Magnetic Sensitivity	5 Gauss, 0.5 inch max

- 1. For switches with TTL driver or decoder
- 2. For switches with indicator

RF PERFORMANCE CHARACTERISTICS								
Frequency	DC-6 GHz	6-12.4 GHz	12.4-18 GHz	18-26.5 GHz	26.5-40 GHz	40-50 GHz	50-67 GHz	
Insertion Loss (max)	0.30 dB	0.40 dB	0.50 dB	0.70 dB	0.80 dB	1.10 dB	1.10 dB	
Isolation (min)	70 dB	60 dB	60 dB	55 dB	50 dB	50 dB	50 dB	
VSWR (max)	1.30:1	1.40:1	1.50:1	1.70:1	1.90:1	1.90:1	1.90:1	

Please see charts on page 4.

### PART NUMBERING SYSTEM



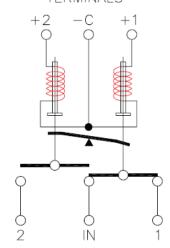
For additional features and options please contact factory.



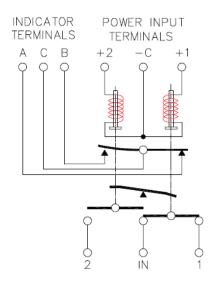
# TTL LOGIC TABLE AND SCHEMATICS

TRUTH TABLE (w/ TTL Option)								
Logic Input		RF	RF Path			Indicator (if applicable)		
1	2	IN to 1	IN to 2		Α	В		
0	0	No C	No Change					
1	0	On	Off	-	С	0		
0	1	Off	On	_	0	С		
1	1	Forb	Forbidden					

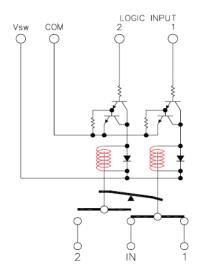
# POWER INPUT TERMINALS



**Analog Input Terminals** 



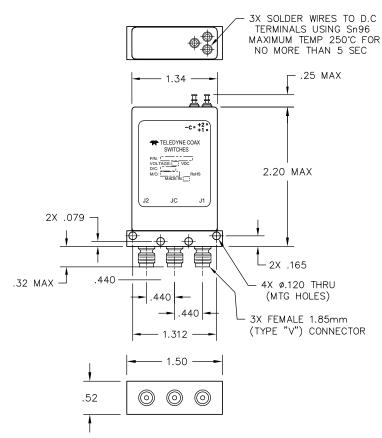
Analog Input Terminals with Indicators

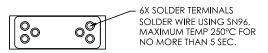


**TTL Driver** 

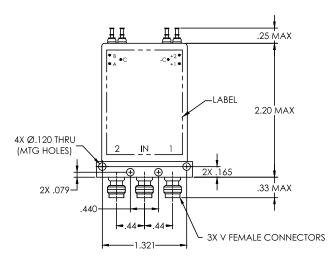


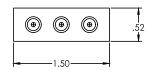
## **MECHANICAL OUTLINES**





# **Standard Model**





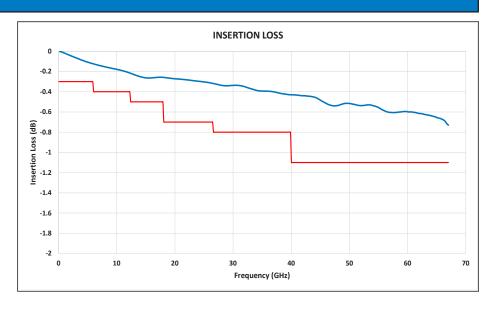
**Indicator Model** 

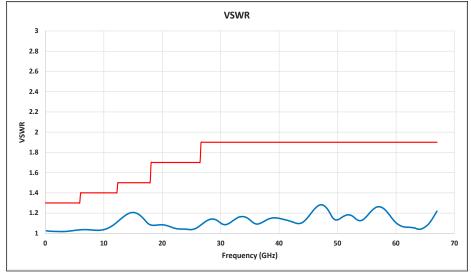
For additional model outlines please contact factory

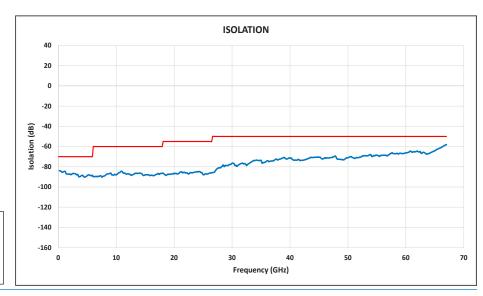


DC-67 GHz, Non-terminated Latching SPDT Coaxial Switch

# RF PERFORMANCE CURVES







TYPICAL

MAXIMUM TEST
LIMIT



#### **GLOSSARY**

#### **Actuator**

An actuator is the electromechanical mechanism that transfers the RF contacts from one position to another upon DC command.

### **Arc Suppression Diode**

A diode is connected in parallel with the coil. This diode limits the "reverse EMF spike" generated when the coil de-energizes to 0.7 volts. The diode cathode is connected to the positive side of the coil and the anode is connected to the negative side.

#### **Date Code**

All switches are marked with either a unique serial number or a date code. Date codes are in accordance with MIL-STD-1285 Paragraph 5.2.5 and consist of four digits. The first two digits define the year and the last two digits define the week of the year (YYWW). Thus, 1032 identifies switches that passed through final inspection during the 32nd week of 2010.

#### Fail-safe

A fail-safe switch reverts to the default or fail-safe position when actuating voltage is removed. This is realized by a return spring within the drive mechanism. This type of switch requires the continuous application of operating voltage to select and hold any position. (Multi-position switches are normally open with no voltage applied).

#### Latching

A latching switch remains in the selected position whether or not voltage is maintained. This can be accomplished with either a magnetic or mechanical latching mechanism.

#### Indicator

Indicators tell the system which position the switch is in. Other names for indicators are telemetry contacts or tell back circuit. Indicators are usually a set of internally mounted DC contacts linked to the actuator. They can be wired to digital input lines, status lights, or interlocks. Unless otherwise specified, the maximum indicator contact rating is 30 Vdc, 50 mA, or 1.5 Watts into a resistive load.

#### **Internal Termination**

ports are Unselected internally terminated to a matched load. The load is  $50\Omega$  resistive device. The max RF power rating is 2 Watts CW. Without the internal termination option, the unselected ports are open circuits.

#### Isolation

Isolation is the measure of the power level at the output connector of an unconnected RF channel as referenced to the power at the input connector. It is specified in dB below the input power level.

#### Self-Cutoff

The self-cutoff option disables the actuator current on completion of actuation. Either a series contact (linked to the actuator) or an IC driver circuit provides the current cutoff. This option results in minimum power consumption by the RF switch. Cutthroat is another name used in the industry for this option. Pulse latching is a term used to describe a switch without this feature.

#### **SPDT Switch**

A single-pole-double-throw, has one input and two output ports.

### **Switching Time**

Switching time is the total interval beginning with the arrival of the leading edge of the command pulse at the switch DC input and ending with the completion of the switch transfer, including contact bounce. It consists of three parts: (1) inductive delay in the coil, (2) transfer time of the physical movement of the contacts, and (3) the bounce time of the RF contacts.

### **TTL Switch Driver Option**

As a special option, switch drivers can be provided for both fail-safe and latching switches, which are compatible with industry-standard lowpower Schottky TTL circuits.

### **Performance Parameters vs** Frequency

Generally speaking, the performance of coaxial switches is frequency dependent. With increasing frequency, VSWR and insertion loss increase while isolation decreases.

All data sheets specify these three parameters as "worst case" at the highest operating frequency. If the switch is to be used over a narrow frequency band, better performance can be achieved.

#### **Actuator Current vs Temperature**

The resistance of the actuator coil varies as a function of temperature. There is an inverse relationship between the operating temperature of the switch and the actuator drive current. For switches operating at 28 VDC, the approximate actuator drive current at temperature, T, can be calculated using the equation:

$$I_{T} = \frac{I_{A}}{[1 + .00385 (T-20)]}$$

#### Where:

I<sub>T</sub> = Actuator current at temperature, T

 $I_{\Delta}$  = Room temperature actuator current – see data sheet

T = Temperature of interest in °C

#### **Magnetic Sensitivity**

An electromechanical switch can be sensitive to ferrous materials and external magnetic fields. Neighboring ferrous materials should be permitted no closer than 0.5 inches and adjacent external magnetic fields should be limited to a flux density of less than 5 Gauss.